Oriental motor



(RoHS) RoHS-Compliant

5 Phase Stepping Motor Unit

CRK Series

Type with Built-In Controller 24 VDC Microstep Drive



5 Phase Microstep Stepping Motor Unit with DC-Input and Integrated Controller. Two Control Methods Including I/O-Control can be selected.

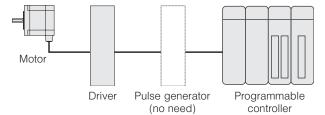




Features

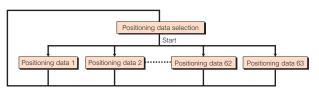
Space-Saving, Less Wiring

The compact driver and the needlessness of a pulse generator make the device space-saving and the system simpler.



Positioning Data of up to 63 Points

Up to 63 points of positioning data can be set in the driver. Each data can be set either in the incremental mode or in the absolute mode.



 \cdot The positioning data can be set with the control module OPX-2A (sold separately) or via RS-485 connection.

Three Operating Patterns

Positioning Operation

The motor operation speed and movement distance are set in the positioning data and the operation is realized based on the selected positioning data. Continuous operation and sequential operation can be selected.

Speed Control Operation

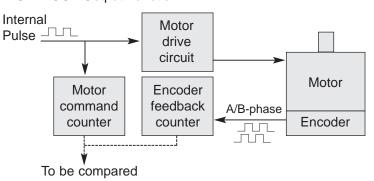
With FWD signal input and RVS signal input the motor operates continuously. As the operation runs with the prior set positioning data, multi-speed operation can be realized by changing the data number.

Return to Home Operation

This function allows an easy return to home operation by using sensors.

Useful Functions

STEPOUT Output Function



- PLS-OUT Output Function
- Multi-axes Operation Function
- Sensor Input Function
- Teaching Function

· When a commanded position to the motor and a feedback position from the encoder are compared, and an abnormal deviation is detected, STEPOUT (Misstep detection output) is turned on. Warning, or Alarm can be generated as well.

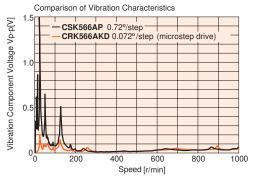
• The motor resolution need not correspond with the encoder resolution because the resolution is matched by the internal encoder electronic gear function.



Low Vibration, Low Noise

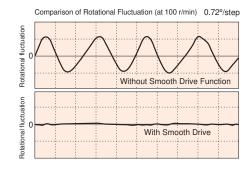
Lower Vibration and Noise Achieved by Microstep Drive

The basic step angle of the motor can be divided into a maximum of 250 microstep angles without using any mechanical element such as a reduction gear. As a result, vibration and noise are further reduced.



Smooth Drive Function for Enhanced Ease of Use

The Smooth Drive Function automatically controls operations via microstep drive, at the same travel distance and speed used in the full-step mode.



Compact Driver for DIN Rail Mounting

Compact DC-Input Driver with Mounting Case

The driver has a compact size of 35 mm (width) x 100 mm (height) x 70 mm (depth) and therefore contributes to a space-saving control box and device.



DIN Rail Mounting Possible

The driver is made for direct DIN rail mounting, screws are not necessary.



Lineup

The standard type and **TH** geared type are available with 42 mm and 60 mm frame size, in total 32 types are provided.

Standard Type





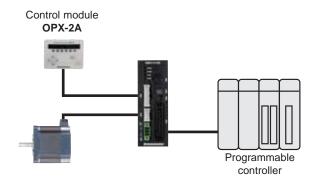
TH Geared Type





Two control methods

I/O controlled system

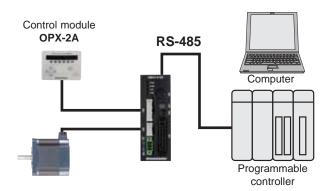


I/O control

Setting and input method of operation command

Setting of operation command and parameter	Operation command (START, STOP, etc.)
Control module (OPX-2A)	I/O

RS-485 controlled system



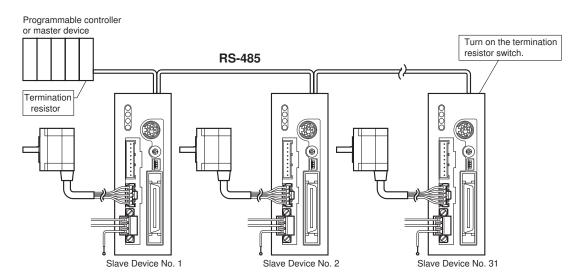
RS-485 control

Setting and input method of operation command

Setting of operation command and parameter	Operation command (START, STOP, etc.)
Control module (OPX-2A)	I/O
RS-485 communication	RS-485 communication

RS-485 communication - Example of system configuration

Connection example



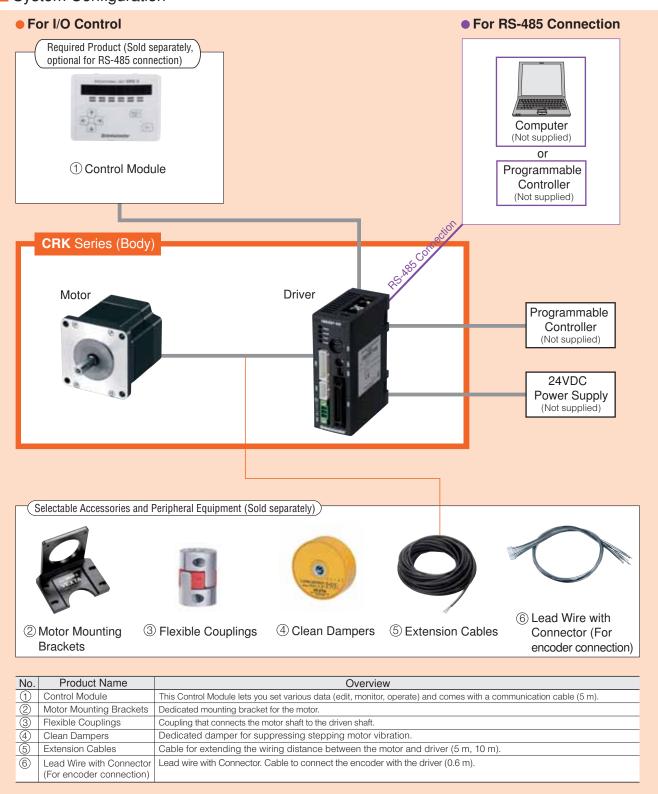
- Up to 31 units can be connected to a host master.
- Operation data and parameter can be set by the RS-485 communication and OPX-2A.
- Both the I/O and the RS-485 communication can be used for inputting the operation command.

Example:

STOP input ⇒ I/O control

START input ⇒ RS-485 communication control

System Configuration



Example of System Configuration

For I/O Control:

	••					
CRK Series	Control Module		Extension Cable (5m)	Motor Mounting Bracket	Flexible Couplina	Clean Damper
CRK566BKD	OPX-2A	Т	CC05PK5	PAL2P-5	MCS300808	D6CL-8.0F

For RS-485 Connection:

CRK Series		Control Module	Extension Cable (5m)	Motor Mounting Bracket	Flexible Coupling	Clean Damper			
CRK566BKD	+	OPX-2A	CC05PK5	PAL2P-5	MCS300808	D6CL-8.0F			

The system configuration shown above is an example. Other combinations are available.

■ Product Number Code

CRK 5 6 4 A K D - T 10 3 4 5 6 7

(1)	Series	CRK Series
2	5 : 5-phase	
3	Motor Frame Size	4 : 42 mm 6 : 60 mm
4	Motor Case Length	
(5)	Motor Shaft Type	A: Single shaft B: Double shaft
6	Power Supply Input	K: DC24V
7	Driver Type	D: Stored data type
8	Gearhead Type	None: Standard type T: TH geared type
9	Gear Ratio	

Standard Type Motor Frame Size 42 mm, 60 mm

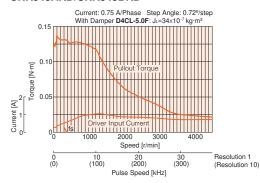
Specifications (RoHS)

CE

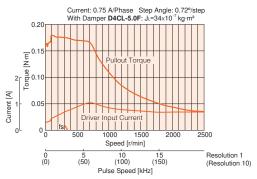
	Single Shaft	CRK543AKD	CRK544AKD	CRK545AKD	CRK564AKD	CRK566AKD	CRK569AKD	
	Double Shaft	CRK543BKD	CRK544BKD	CRK545BKD	CRK564BKD	CRK566BKD	CRK569BKD	
Maximum Holding Torque	. N·m	0.13	0.18	0.24	0.42	0.83	1.66	
Rotor Inertia	J∶kg·m²	35×10 ⁻⁷	54×10 ⁻⁷	68×10 ⁻⁷	175×10 ⁻⁷	280×10 ⁻⁷	560×10 ⁻⁷	
Rated Current	A/Phase		0.75		1.4			
Basic Step Angle				0.	72°			
Power Source			24 VDC±10% 1.4	A		24 VDC±10% 2.5	A	
Excitation Mode				Micro	ostep			
Mass	Motor kg	0.25	0.3	0.4	0.6	0.8	1.3	
	Driver kg	0.2						
Dimension No.	Motor		1			2		
Difficiation No.	Driver	·	·	į	5			

Speed - Torque Characteristics fs: Starting Frequency

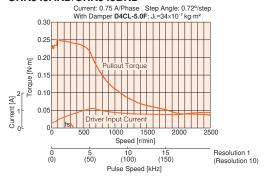
CRK543AKD/CRK543BKD



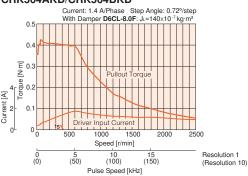
CRK544AKD/CRK544BKD



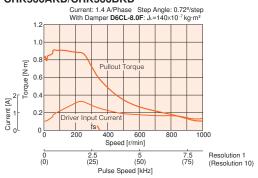
CRK545AKD/CRK545BKD



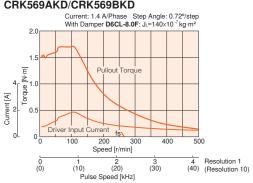
CRK564AKD/CRK564BKD



CRK566AKD/CRK566BKD



CRK569AKD/CRK569BKD



- Pay attention to heat dissipation from motor as there will be a considerable amount of heat under certain conditions. Be sure to keep the temperature of the motor case under 100°C.
 The driver's automatic current cutback function at motor standstill reduces maximum holding torque by approximately 50 %.

■TH Geared Type Motor Frame Size 42 mm

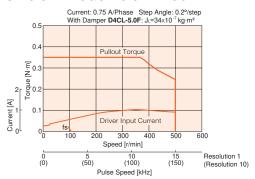
Specifications (RoHS)

CE

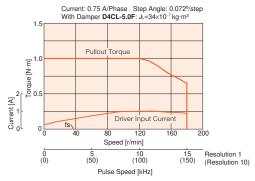
S	ingle Shaft	CRK543AKD-T3.6	CRK543AKD-T7.2	CRK543AKD-T10	CRK543AKD-T20	CRK543AKD-T30
D	ouble Shaft	CRK543BKD-T3.6	CRK543BKD-T7.2	CRK543BKD-T10	CRK543BKD-T20	CRK543BKD-T30
Maximum Holding Torque	N⋅m	0.35	0.7	1	1	.5
Rotor Inertia	J: g·m²		35×10 ⁻⁷			
Rated Current	A/Phase			0.75		
Basic Step Angle		0.2°	0.1°	0.072°	0.036°	0.024°
Gear Ratio		1:3.6	1: 7.2	1: 10	1:20	1:30
Permissible Torque	N⋅m	0.35	0.7	1	1.5	
Backlash	degrees	0.75°	0	.417°	0	.25°
Permissible Speed Range	r/min	0~500	0~250	0~180	0~90	0~60
Power Source				24 VDC±10% 1.4	A	
Excitation Mode				Microstep		
Mass	Motor kg	0.35				
	Driver kg	0.2				
Dimension No.	Motor			3		
	Driver		·	5		·

Speed - Torque Characteristics fs: Starting Frequency

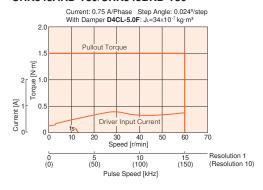
CRK543AKD-T3.6/CRK543BKD-T3.6



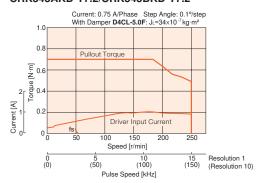
CRK543AKD-T10/CRK543BKD-T10



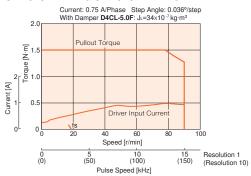
CRK543AKD-T30/CRK543BKD-T30



CRK543AKD-T7.2/CRK543BKD-T7.2



CRK543AKD-T20/CRK543BKD-T20



- Notes:
 Pay attention to heat dissipation from motor as there will be a considerable amount of heat under certain conditions. Be sure to keep the temperature of the motor case under 100°C.
- $\cdot \text{ The driver's automatic current cutback function at motor standstill reduces maximum holding torque by approximately 50 \%}$

Notes:
• Direction of rotation of the motor and that of the gear output shaft are the same for the gear ratios 1:3.6, 1:7.2 and 1:10. It is the opposite for 1:20 and 1:30 gear ratios.

■TH Geared Type Motor Frame Size 60 mm

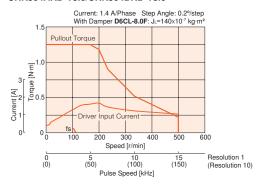
Specifications (RoHS)

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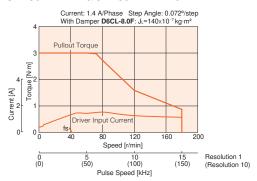
	Single Shaft	CRK564AKD-T3.6	CRK564AKD-T7.2	CRK564AKD-T10	CRK564AKD-T20	CRK564AKD-T30		
	Double Shaft	CRK564BKD-T3.6	CRK564BKD-T7.2	CRK564BKD-T10	CRK564BKD-T20	CRK564BKD-T30		
Maximum Holding Torqu	e N·m	1.25	2.5	3	3.5	4		
Rotor Inertia	J: g⋅m²			175×10 ⁻⁷		_		
Rated Current	A/Phase		1.4					
Basic Step Angle		0.2°	0.1°	0.072°	0.036°	0.024°		
Gear Ratio		1:3.6	1: 7.2	1:10	1: 20	1:30		
Permissible Torque	N⋅m	1.25	2.5	3	3.5	4		
Backlash	degrees	0.584°	0	.25°	0.	.167°		
Permissible Speed Range	e r/min	0~500	0~250	0~180	0~90	0~60		
Power Source				24 VDC±10% 2.5	A			
Excitation Mode				Microstep				
Mass	Motor kg			0.95				
IVIGOS	Driver kg		0.2					
Dimension No.	Motor			4				
	Driver		5					

Speed - Torque Characteristics fs: Starting Frequency

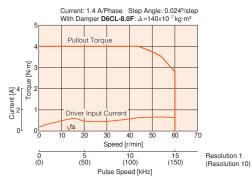
CRK564AKD-T3.6/CRK564BKD-T3.6



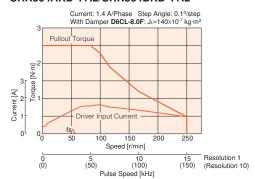
CRK564AKD-T10/CRK564BKD-T10



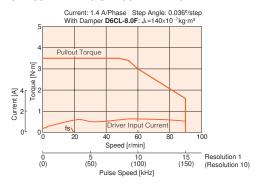
CRK564AKD-T30/CRK564BKD-T30



CRK564AKD-T7.2/CRK564BKD-T7.2



CRK564AKD-T20/CRK564BKD-T20



- Notes:
 Pay attention to heat dissipation from motor as there will be a considerable amount of heat under certain conditions. Be sure to keep the temperature of the motor case under 100°C.
- The driver's automatic current cutback function at motor standstill reduces maximum holding torque by approximately 50 %.

Direction of rotation of the motor and that of the gear output shaft are the same for the gear ratios 1:3.6, 1:7.2 and 1:10. It is the opposite for 1:20 and 1:30 gear ratios.

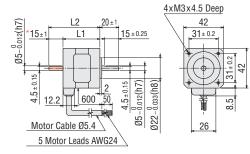
■ Dimensions (Unit = mm)

Motor

Standard Type

1 □ 42 mm

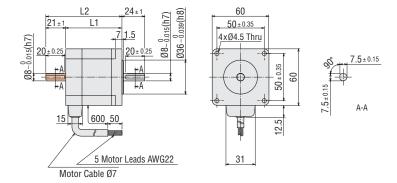
Model	Motor Model	L1	L2	Mass (kg)
CRK543AKD	PK543AW	33	_	0.25
CRK543BKD	PK543BW	33	48	0.25
CRK544AKD	PK544AW	39	_	0.3
CRK544BKD	PK544BW	39	54	0.3
CRK545AKD	PK545AW	47	_	0.4
CRK545BKD	PK545BW	4/	62	0.4



 $^{^{\}star}$ The length of machining on double shaft model is 15 $\pm\,0.25$ mm.

2 □ **60 mm**

Model	Motor Model	L1	L2	Mass (kg)
CRK564AKD	PK564AW	48.5	_	0.6
CRK564BKD	PK564BW	46.5	69.5	0.6
CRK566AKD	PK566AW	59.5	_	0.8
CRK566BKD	PK566BW	59.5	80.5	0.8
CRK569AKD	PK569AW	89	_	1.3
CRK569BKD	PK569BW	89	110	1.3

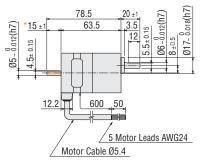


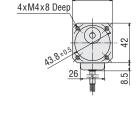
TH Geared Type

3 **□ 42 mm**

Model	Motor Model	Gear Ratio	Mass (kg)
CRK543AKD-T□	PK543AW-T □	26 70 10 00 00	0.05
CRK543BKD-T□	PK543BW-T □	3.6, 7.2, 10, 20, 30	0.35

[·] Enter the gear ratio in the box () within the model name.



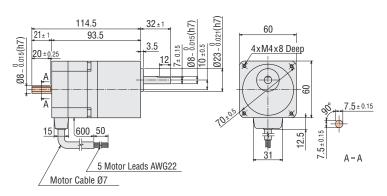


^{*} The length of machining on double shaft model is 15 ± 0.25 mm.

4 □ 60 mm

Model	Motor Model	Gear Ratio	Mass (kg)
CRK564AKD-T□	PK564AW-T □	26 70 10 00 00	0.05
CRK564BKD-T□	PK564BW-T □	3.6, 7.2, 10, 20, 30	0.95

[·] Enter the gear ratio in the box (□) within the model name.



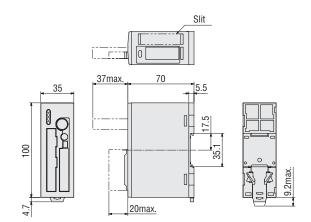
[•] These dimensions are for double shaft models. For single shaft models, ignore the orange _____ areas.

■ Dimensions (Unit = mm)

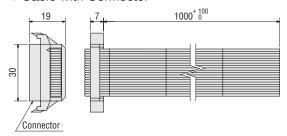
Driver

5 Driver Model: CRD507-KD, CRD514-KD

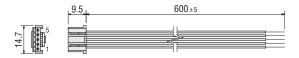
Mass: 0.2 kg



Cable with Connector



• Lead Wire with Connector (For Motor Connection)



Power Supply Connector (CN1)

· Connector: MC1,5/3-STF-3,5 (PHOENIX CONTACT)

Cable with Connector (CN2, length: 1 m)

· Connector: FX2B-40SA-1.27R (HIROSE Electric)

Lead Wire with Connector (for motor connection) (CN4, length: 0.6 m)

· Connector Housing: 51103-0500 (MOLEX)

· Contact: 50351-8100 (MOLEX) · Hand Crimper: 57295-5000 (MOLEX)

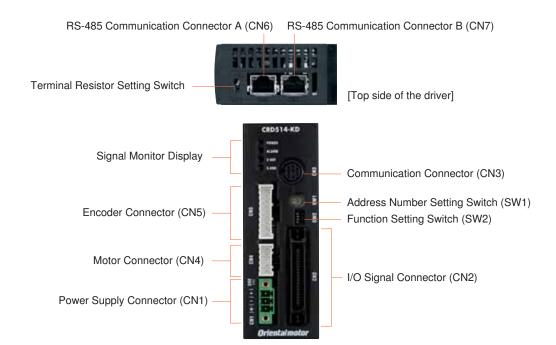
• In case of ordering only the driver for example for repair, the lead wire with connector, the cable with connector and the power supply connector are included.

Product Line

Type	Motor Frame Size	Model	Motor Model	Driver Model
Standard	□ 42 mm	CRK543AKD	PK543AW	CRD507-KD
Type		CRK543BKD	PK543BW	
71.		CRK544AKD	PK544AW	
		CRK544BKD	PK544BW	
		CRK545AKD	PK545AW	
		CRK545BKD	PK545BW	
	□ 60 mm	CRK564AKD	PK564AW	
		CRK564BKD	PK564BW	CRD514-KD
		CRK566AKD	PK566AW	
		CRK566BKD	PK566BW	
		CRK569AKD	PK569AW	
		CRK569BKD	PK569BW	
TH Geared	□ 42 mm	CRK543AKD-T3.6	PK543AW-T3.6	
Type		CRK543BKD-T3.6	PK543BW-T3.6	CRD507-KD
,,		CRK543AKD-T7.2	PK543AW-T7.2	
		CRK543BKD-T7.2	PK543BW-T7.2	
		CRK543AKD-T10	PK543AW-T10	
		CRK543BKD-T10	PK543BW-T10	
		CRK543AKD-T20	PK543AW-T20	
		CRK543BKD-T20	PK543BW-T20	
		CRK543AKD-T30	PK543AW-T30	
		CRK543BKD-T30	PK543BW-T30	
	□ 60 mm	CRK564AKD-T3.6	PK564AW-T3.6	
		CRK564BKD-T3.6	PK564BW-T3.6	
		CRK564AKD-T7.2	PK564AW-T7.2	
		CRK564BKD-T7.2	PK564BW-T7.2	
		CRK564AKD-T10	PK564AW-T10	CRD514-KD
		CRK564BKD-T10	PK564BW-T10	31.5311165
		CRK564AKD-T20	PK564AW-T20	
		CRK564BKD-T20	PK564BW-T20	
		CRK564AKD-T30	PK564AW-T30	
		CRK564BKD-T30	PK564BW-T30	

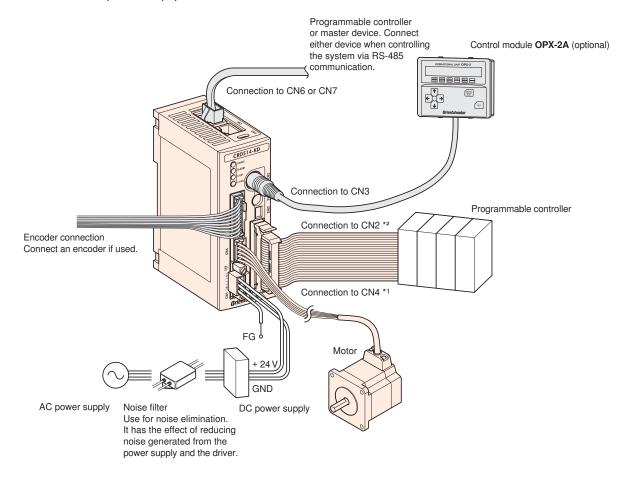
Connection and Operation

Names and Functions of Driver Parts



Connection Diagrams

Connection to Peripheral Equipment



^{*1} When ordering the unit or only the driver the 0.6 m lead wire with connector is included.

^{*2} When ordering the unit or only the driver the 1 m cable with connector is included.

Accessories (Sold separately)

Control Module RoHS

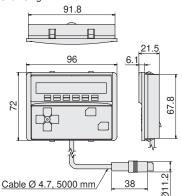
You can change the positioning data, various parameter and you can use it as a monitor.

Product Line Model OPX-2A

■ Dimensions (Unit = mm)

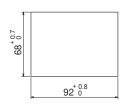
Control Module

Mass: 0.25 kg



Panel Cut-Out for Control

(Thickness of the mounting plate: 1-3 mm)





Lead Wire with Connector

For Motor Connection

Crimped lead wire for the connection of motor and driver. When ordering a unit, a 0.6 m lead wire with connector is included.

For Encoder Connection

Crimped lead wire for the connection of encoder and driver.

Product Line

Model	Purpose	Length L(mm)	Conductor AWG
LC5N06B	For motor connection	600	22 (0.3 mm²)
LC5N10B	For motor connection	1000	
LC09A-006	For encoder connection	600	





For motor connection

For **encoder** connection

RS-485 Communication Cable

Length L (m)

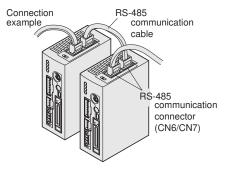
Cable to connect the drivers in case of multi-axes operation.

Product Line

Model

CC001-RS4	0.1	
<u> </u>	110 + 10	<u>.</u>
		21.7
	\Ø5.5	





Orientalmotor

This product is manufactured at a plant certified with the international standards ISO 9001 (for quality assurance) and ISO 14001 (for systems of environmental management).

Specifications are subject to change without notice.

This catalogue was published in May, 2009.

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[·] For more Accessories please check on page 5.