

30W

□60mm

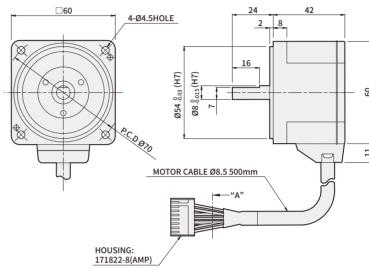
DC24V Input

DIMENSIONS

K6LS30N2

(Weight: 0.5Kg)

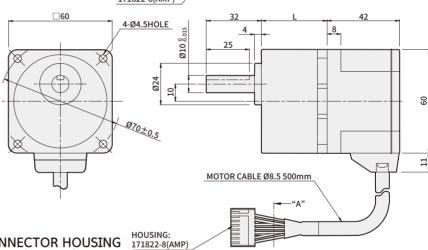




K6LH30N2 + K6H□B

(Weight: 0.9Kg)





* KEY \cdot KEY GROOVE (ACCESSORY) * CONNECTOR HOUSING (VIEW A)





MOTOR PRODUCT NAME	GEARHEAD PRODUCT NAME	DECELERATION RATIO	L	FIXING BOLT
		5~20	34	M4 P0.7×50
K6LH30N2	К6Н□В	30~100	38	M4 P0.7×55
		200	43	M4 P0.7×60

* FIN WAP								
PIN No.	COLOR	SIGNAL						
1	GRAY	W						
2	PURPLE	V						
3	BLUE	U						
4	YELLOW	Vcc						
5	GREEN	Ground						
6	ORANGE	Hw						
7	WHITE	Hv						
8	BROWN	Hu						

^{*} In \square of name, it represents a deceleration ratio.

^{*} Geared motor is included with fixing bolt set. (flat washer, spring washer, hexagonal nut 4pcs each)

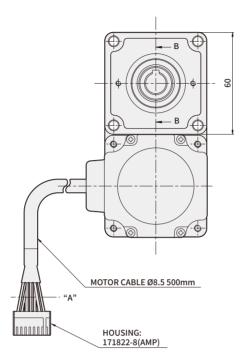


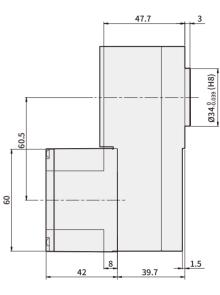
DIMENSIONS

K6LH30N2 + K6H□BTH

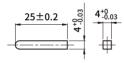
(Weight: 1.2Kg)





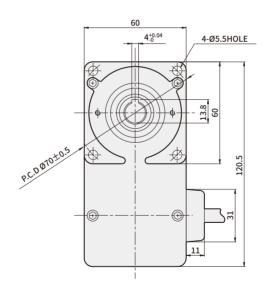


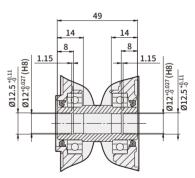
* KEY (ACCESSORY)



* CONNECTOR HOUSING (VIEW A)







SECTION B-B

PIN No.	COLOR	SIGNAL
1	GRAY	W
2	PURPLE	V
3	BLUE	U
4	YELLOW	Vcc
5	GREEN	Ground
6	ORANGE	Hw
7	WHITE	Hv
8	BROWN	Hu

MOTOR PRODUCT NAME	GEARHEAD PRODUCT NAME	DECELERATION RATIO	FIXING BOLT
K6LH30N2	К6Н□ВТН	5~200	M5 P0.8×65

- * In □ of name, it represents a deceleration ratio.
- * Mounting bolt sets are included in flat type gearbox. M5×65L (flat washer, spring washer, hexagonal nut 4pcs each)



Specification

Product		GEAR TYPE	K6LH30N2	K8LH50N2	K9LH100N2	K10LH200N2	K10LH400N9	
name		STRAIGHT TYPE	K6LS30N2	K8LS50N2	K9LS100N2	K10LS200N2	K10LS400N9	
Rating o	utput (con	tinuous) W	30	50	100	200	400	
	Rating vol	tage V		DC	24		DC 48	
Power	Rating vol	tage allowance			±10%			
input	Rating inp	ut current A	2.1	3.1	6	13	11	
	Rating out	tput current A	3.7	5.4	9.8	25	18	
Rating to	orque	N·m(kgf·cm)	0.12	0.2	0.4	0.65	1.3	
Starting	torque	N·m(kgf·cm)	0.15	0.24	0.5	1.15	1.8	
Rating ro	tation speed	r/min	2500			3000		
Speed co	ntrol range	r/min	100~3000			100~4000		
moment o	inertia load f round shaft ype	J×10⁻⁴ kg·m²	1.8	3.3	5.6	8.75	15	
Rotor ine	rtia moment	J×10⁻⁴ kg·m²	0.086	0.234	0.61	0.61	0.66	
Load			Less than or equal to ±1%: condition 0-rated torque, rated rotation speed, rated voltage, room temperature					
Speed change rate		Voltage	Less than or equal to ±1% : condition rating voltage ±10%, rating rotation speed, no load, room temperature					
Tempera			Less th	an or equal to ±1% rating rotat	condition surrou ion speed, no load,		0~+40℃,	

- * The usage duration for starting torque is within 5 seconds at less than 2000 r/min
- * Each specification value is the characteristic of motor by itself

Common specifications

Product name	Specification
Rotation speed setting method	 Set up by external potentiometer Set up by external DC 0~5V
Acceleration time deceleration time	0.5~10 seconds: set at 2000 r/min when there is no load (it may change depending on the size of the load) Accleration time and deceleration control equipment to control at the same time
Input signal	Internal full-up input method, external input voltage read as greater than 2v high(off) same at all input ports
Output signal	Open collector output, common for speed out/alarm out, if input voltage from out side is applied to connector #2 pin, then it comes out through the applied power. Everything else is internal 5V ouput UI(CTRL)
Protection function	If the following protection mode comes on, cotrol unit alarm signal is shown. Motor stops automatically. Overload protection mode: If torque that is greater than the rating is applied to the motor for more than 5 seconds Overvoltage protection: If voltage applied to the control unit goes over the upper bound of the rating allowance Open phase protection: If cable sensor line gets disconnected during motor operation Undervoltage protection: If voltage applied to the control unit is less than the lower bound of th rating voltage allowance Over speed protection: If motor rotation speed is faster than 2500 r/min
Motor insulation class	E TYPE(120°c)
Maximum extension distance	MOTOR - CONTROL UNIT 2m
Rated time	Continuous

^{*} Like weight carried being downwards, L SERIES cannot control motor speed through weight.

Motor gets stopped automatically through overvoltage protection of load is being carried downwards or it is heavier than allowed load inertia.





Normal specifications

Iter	ns	Motor	Control unit				
Insulation Resistance		After being operated continuously at room temperature and humidity, the value measured between coil and vase by DC 500V MEGA is greater than or equal to 100№	After being operated continuously at room temperature and humidity, the value measured between heatproof plate and power input is greater than or equal to 100MQ				
Dielectric Strength		After being operated continuously at room temperature and humidity, there shouldn't be any problem between coil and case even when AC 0.5kV is applied for 1 minute	No problem when 50Hz, AC 0.5kV is applied for one minute No problem when AC 0.5kV is applied for one minute				
	Used Ambient temperature	0℃~+50℃ (shc	ould not freeze)				
	Used Ambient Humidity	less than or equal to 85% (not from dews)					
Used	Vibration	Altitude less than 1000m					
environment	Ambient environment	Cannot be used under special circumstances such as with corrosive gas, dust, radioactive material, magnetic and vacuum					
	Vibration	the JIS C 60068-2-6 sine v Frequency range : 10~55Hz	tion or huge impact according to vave vibration test method r, peak amplitude: 0.15mm, ,Z), number of sweeps: 20 times				
	Ambient temperature	-25 ~ +70° (sh	ould not freeze)				
Conservation environment	Ambient Humidity	less than or equal to 8	35% (not form dews)				
	Altitude	Altitude less than 3000m					
Insulatio	on class	UL, CSA STANDARD A TYPE(105°c), EN STANDARD E TYPE(120°c)					
Protection class		IP65	IP00				

- * Preservation environment is a short-term value, which includes transportation.
- * Do not measure insulation resistance and pressure resistance while motor and driver are connected

Delivery effciency of gearhead

	Deceleration ratio	5	10	15	20	30	50	100	200
	К6Н□В		90)%		86%			81%
	K8H□B		90)%		86%			81%
Product	К9Н□В		90)%		86%			81%
name	K10H□BU		90%				86% 819		
	K6H□BTH	80%				85%			
	K8H□BTH	85%							
	K9H□BTH 85					%			



→ Allowed torque of combination type

Product	Deceleration ratio		5	10	15	20	30	50	100	200
name	Speed control	range[r/min]	20~600	10~300	6.7~200	5~150	3.3~100	2~60	1~30	0.5~15
KEDII	30N2 + K6H□B	100~2500r/min	0.54	1.1	1.6	2.2	3.1	5.2	6	6
КОВП	SUNZ + KOHLIB	3000r/min	0.3	0.54	0.81	1.1	1.5	2.6	5.2	6
ГО ВП	50N2 + K8H□B	100~2500r/min	0.9	1.8	2.7	3.6	5.2	8.6	16	16
КОВП	DUNZ + KOHLIB	3000r/min	0.45	0.9	1.4	1.8	2.6	4.3	8.6	16
KOBILI	100N2 + K9H□B	100~2500r/min	1.8	3.6	5.4	7.2	10.3	17.2	30	30
KSDU	IUUNZ + K9HLB	3000r/min	0.9	1.8	2.7	3.6	5.2	8.6	17.2	30
		100~2500r/min	0.48	1	1.5	2	3.1	5.1	10.2	17
Ковнз	ON2 + K6H□BTH	3000r/min	0.2	0.51	0.77	1	1.5	2.6	5.1	10.2
		100~2500r/min	0.85	1.7	2.6	3.4	5.1	8.5	17	34
Ковно	0N2 + K8H□BTH	3000r/min	4.3	8.5	13	17	26	4.3	8.5	17
KODIII	ONI - KOUDDIU	100~2500r/min	1.7	3.4	5.1	6.8	10.2	17	34	68
КЭВНІС	OON2 + K9H□BTH	3000r/min	0.85	1.7	2.6	3.4	5.1	8.5	17	34
Product	Decelerat	ion ratio	5	10	15	20	30	50	100	200
name	Speed control	range[r/min]	20~800	10~400	6.7~267	5~200	3.3~133	2~80	1~40	0.5~20
V101112	00N3 + K10H□BII	100~3000r/min	2.9	5.9	8.8	11.7	16.8	28	52.7	70
K10LH200N2 + K10H□BU		4000r/min	2.0	4.1	6.1	8.1	11.6	19.4	36.5	63
K101114	00N0 + K10H=PH	100~3000r/min	5.9	11.7	17.6	23.4	33.5	55.9	70	70
K TULH4	00N9 + K10H□BU	4000r/min	4.3	8.6	12.8	17.1	24.5	40.9	63	63

^{*} Rotation direction shows the same _____ color as the motor. In other cases, it's the opposite.

^{*} Flat Gearbox viewed from front side is opposite rotation direction with motor.

^{*} Flat Gearbox viewed from back side is same rotation direction with motor.



Allowed overhang load and allowed thrust

Product name				Allowed ov	- Allowed thrust load				
		Deceleration ratio		of output part		of output part	Allowed tillust load		
			N	kgf	N	kgf	N	kgf	
		5	100	10	150	15			
	K6LH30N2 + K6H□B	10,15,20	150	15	200	20	40	4	
		30,50,100,200	200	20	300	30			
		5	200	20	250	25			
	K8LH50N2 + K8H□B	10,15,20	300	30	350	35	100	10	
		30,50,100,200	450	45	550	55			
		5	300	30	400	40			
	K9LH100N2 + K9H□B	10,15,20	400	40	500	50	150	15	
		30,50,100,200	500	50	650	65			
GEARED MOTOR	144 01 110 00 10	5,10,15,20	550	55	800	80	200	20	
	K10LH200N2 (K10LH400N9) + K10H□BU	30,50	1000	100	1250	125	300	30	
	· KIGII	100,200	1400	140	1700	170	400	40	
	K6LH30N2	5,10	450	45	370	37	200	20	
	+ K6H□BTH	15~200	500	50	400	40	200	20	
	K8LH50N2	5,10	800	80	660	66	400	40	
	+ K8H□BTH	15~200	1200	120	1000	100	400	40	
		5,10	900	90	770	77			
	K9LH100N2 + K9H□BTH	15,20	1300	130	1110	111	500	50	
		30,50,100,200	1500	150	1280	128			
	K6LS	30N2	70	7	100	10			
MOTOR	K8LS	50N2	120	12	140	14		to weigh thrust. e, keep it under	
IVIOTOR	K9LS1	100N2	160	16	170	17	50% of the r	notor weight.	
	K10LS200N2	,K10LS400N9	197	19.7	220	22			

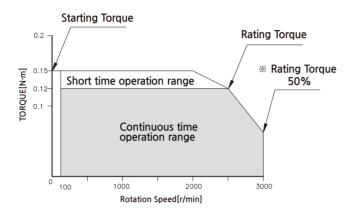
 $[\]star$ In \square of name, it represents a deceleration ratio.

 $[\]star$ Permissible overhang load can be with drawn by calulation.

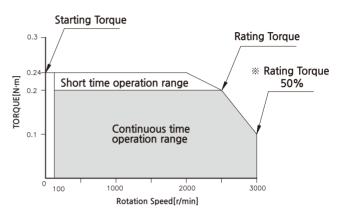


Rotation speed- torque characteristic

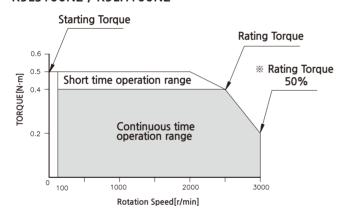
K6LS30N2 / K6LH30N2



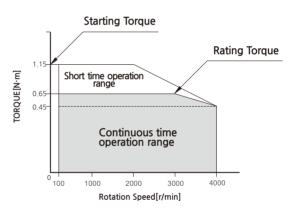
K8LS50N2 / K8LH50N2



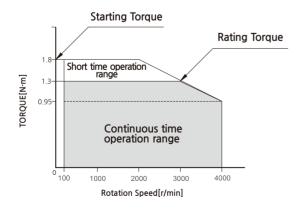
K9LS100N2 / K9LH100N2



K10LS200N2/K10LH200N2



K10LS400N9/K10LH400N9



* DC24V is the value without cable extension.





□80mm

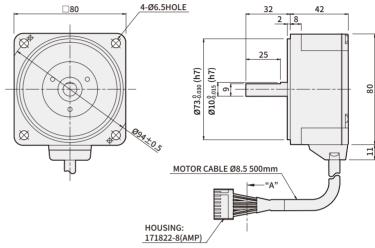
DC24V Input

DIMENSIONS

K8LS50N2

(Weight: 0.8Kg)

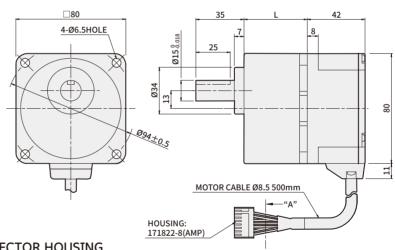




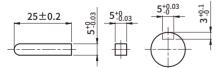
K8LH50N2 + K8H□B

(Weight: 1.7Kg)





* KEY · KEY GROOVE (ACCESSORY)



* CONNECTOR HOUSING (VIEW A)



200

51

M6 P1.0×75

MOTOR PRODUCT NAME	GEARHEAD PRODUCT NAME	DECELERATION RATIO	L	FIXING BOLT
		5~20	41	M6 P1.0×65
K8LH50N2	К8Н□В	30~100	46	M6 P1.0×70

* PTN MAP

* FIN WAP								
PIN No.	COLOR	SIGNAL						
1	GRAY	W						
2	PURPLE	V						
3	BLUE	U						
4	YELLOW	Vcc						
5	GREEN	Ground						
6	ORANGE	Hw						
7	WHITE	Hv						
8	BROWN	Hu						

^{*} In \square of name, it represents a deceleration ratio.

^{*} Geared motor is included with fixing bolt set. (flat washer, spring washer, hexagonal nut 4pcs each)

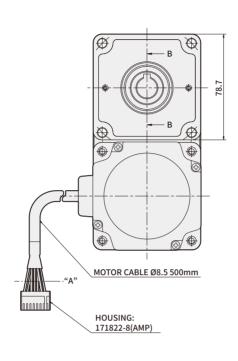


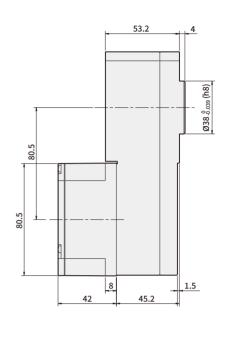
DIMENSIONS

K8LH50N2 + K8H□BTH

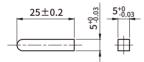
(Weight: 2.3Kg)



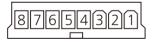


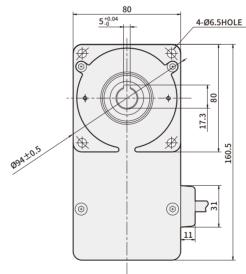


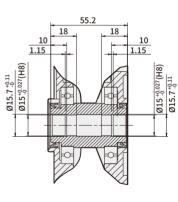
* KEY (ACCESSORY)



* CONNECTOR HOUSING (VIEW A)







SECTION B-B

MOTOR PRODUCT NAME	GEARHEAD PRODUCT NAME	DECELERATION RATIO	FIXING BOLT
K8LH50N2	К8Н□ВТН	5~200	M6 P1.0×70

- * In □ of name, it represents a deceleration ratio.
- * Mounting bolt sets are included in flat type gearbox.

 M6×70L (flat washer, spring washer, hexagonal nut 4pcs each)

PIN No.	COLOR	SIGNAL
1	GRAY	W
2	PURPLE	V
3	BLUE	U
4	YELLOW	Vcc
5	GREEN	Ground
6	ORANGE	Hw
7	WHITE	Hv
8	BROWN	Hu



Specification

Product		GEAR TYPE	K6LH30N2	K8LH50N2	K9LH100N2	K10LH200N2	K10LH400N9	
name		STRAIGHT TYPE	K6LS30N2	K8LS50N2	K9LS100N2	K10LS200N2	K10LS400N9	
Rating output (continuous) W			30	50	100	200	400	
	Rating vol	tage V		DC	24		DC 48	
Power	Rating vol	tage allowance			±10%			
input	Rating inp	ut current A	2.1	3.1	6	13	11	
	Rating out	tput current A	3.7	5.4	9.8	25	18	
Rating to	orque	N·m(kgf·cm)	0.12	0.2	0.4	0.65	1.3	
Starting	Starting torque N·m(kgf·cm)		0.15	0.24	0.5	1.15	1.8	
Rating ro	tation speed	r/min	2500			3000		
Speed co	ntrol range	r/min	100~3000			100~4000		
moment o	inertia load f round shaft ype	J×10⁻⁴ kg·m²	1.8	3.3	5.6	8.75	15	
Rotor ine	rtia moment	J×10⁻⁴ kg·m²	0.086	0.234	0.61	0.61	0.66	
Load			Less than or equal to ±1%: condition 0-rated torque, rated rotation speed, rated voltage, room temperature					
Speed change rate		Voltage	Less than or equal to ±1% : condition rating voltage ±10%, rating rotation speed, no load, room temperature					
idic		Temperature	Less than or equal to $\pm 1\%$: condition surrounding temperature $0\sim +40\%$, rating rotation speed, no load, rating voltage					

- * The usage duration for starting torque is within 5 seconds at less than 2000 r/min
- * Each specification value is the characteristic of motor by itself

Common specifications

Product name	Specification
Rotation speed setting method	 Set up by external potentiometer Set up by external DC 0~5V
Acceleration time deceleration time	0.5~10 seconds: set at 2000 r/min when there is no load (it may change depending on the size of the load) Accleration time and deceleration control equipment to control at the same time
Input signal	Internal full-up input method, external input voltage read as greater than 2v high(off) same at all input ports
Output signal	Open collector output, common for speed out/alarm out, if input voltage from out side is applied to connector #2 pin, then it comes out through the applied power. Everything else is internal 5V ouput UI(CTRL)
Protection function	If the following protection mode comes on, cotrol unit alarm signal is shown. Motor stops automatically. Overload protection mode: If torque that is greater than the rating is applied to the motor for more than 5 seconds Overvoltage protection: If voltage applied to the control unit goes over the upper bound of the rating allowance Open phase protection: If cable sensor line gets disconnected during motor operation Undervoltage protection: If voltage applied to the control unit is less than the lower bound of th rating voltage allowance Over speed protection: If motor rotation speed is faster than 2500 r/min
Motor insulation class	E TYPE(120°c)
Maximum extension distance	MOTOR - CONTROL UNIT 2m
Rated time	Continuous

^{*} Like weight carried being downwards, L SERIES cannot control motor speed through weight.

Motor gets stopped automatically through overvoltage protection of load is being carried downwards or it is heavier than allowed load inertia.





Normal specifications

Items		Motor	Control unit			
Insulation Resistance		After being operated continuously at room temperature and humidity, the value measured between coil and vase by DC 500V MEGA is greater than or equal to 100№	After being operated continuously at room temperature and humidity, the value measured between heatproof plate and power input is greater than or equal to 100MQ			
Dielectric Strength		After being operated continuously at room temperature and humidity, there shouldn't be any problem between coil and case even when AC 0.5kV is applied for 1 minute	No problem when 50Hz, AC 0.5kV is applied for one minute No problem when AC 0.5kV is applied for one minute			
	Used Ambient temperature	0℃~+50℃ (shc	ould not freeze)			
	Used Ambient Humidity	less than or equal to 85% (not from dews)				
Used	Vibration	Altitude less than 1000m				
environment	Ambient environment	Cannot be used under special circumstances such as with corrosive gas, dust, radioactive material, magnetic and vacuum				
	Vibration	the JIS C 60068-2-6 sine v Frequency range : 10~55Hz	tion or huge impact according to vave vibration test method r, peak amplitude: 0.15mm, ,Z), number of sweeps: 20 times			
	Ambient temperature	-25 ~ +70° (sh	ould not freeze)			
Conservation environment	Ambient Humidity	less than or equal to 8	35% (not form dews)			
	Altitude	Altitude less than 3000m				
Insulatio	on class	UL, CSA STANDARD A TYPE(105°c), EN STANDARD E TYPE(120°c)				
Protection	on class	IP65	IP00			

- * Preservation environment is a short-term value, which includes transportation.
- * Do not measure insulation resistance and pressure resistance while motor and driver are connected

Delivery effciency of gearhead

	Deceleration ratio	5	10	15	20	30	50	100	200
	К6Н□В		90%				86%		
	K8H□B		90%				86%		
Product	К9Н□В	90%				86%			81%
name	K10H□BU		90%			86%		%	
	K6H□BTH	80%	80% 85%						
	K8H□BTH		85%						
	K9H□BTH	85%							



→ Allowed torque of combination type

Product	Decelerat	ion ratio	5	10	15	20	30	50	100	200
name	Speed control	range[r/min]	20~600	10~300	6.7~200	5~150	3.3~100	2~60	1~30	0.5~15
		100~2500r/min	0.54	1.1	1.6	2.2	3.1	5.2	6	6
КОВП	30N2 + K6H□B	3000r/min	0.3	0.54	0.81	1.1	1.5	2.6	5.2	6
ГО ВП	50N2 + K8H□B	100~2500r/min	0.9	1.8	2.7	3.6	5.2	8.6	16	16
КОВП	DUNZ + KOHLIB	3000r/min	0.45	0.9	1.4	1.8	2.6	4.3	8.6	16
KOBILI	100N2 + K9H□B	100~2500r/min	1.8	3.6	5.4	7.2	10.3	17.2	30	30
KSDU	IUUNZ + K9HLB	3000r/min	0.9	1.8	2.7	3.6	5.2	8.6	17.2	30
K6BH30N2 + K6H□BTH		100~2500r/min	0.48	1	1.5	2	3.1	5.1	10.2	17
		3000r/min	0.2	0.51	0.77	1	1.5	2.6	5.1	10.2
KODITE	10		0.85	1.7	2.6	3.4	5.1	8.5	17	34
Ковно	0N2 + K8H□BTH	3000r/min	4.3	8.5	13	17	26	4.3	8.5	17
KODIII	ONI - KOUDDIU	100~2500r/min	1.7	3.4	5.1	6.8	10.2	17	34	68
КЭВНІС	OON2 + K9H□BTH	3000r/min	0.85	1.7	2.6	3.4	5.1	8.5	17	34
Product	Decelerat	ion ratio	5	10	15	20	30	50	100	200
name		range[r/min]	20~800	10~400	6.7~267	5~200	3.3~133	2~80	1~40	0.5~20
V101112	00N3 + K10H□BII	100~3000r/min	2.9	5.9	8.8	11.7	16.8	28	52.7	70
K10LH200N2 + K10H□BU		4000r/min	2.0	4.1	6.1	8.1	11.6	19.4	36.5	63
K101114	00N0 + K10H=PH	100~3000r/min	5.9	11.7	17.6	23.4	33.5	55.9	70	70
K TULH4	00N9 + K10H□BU	4000r/min	4.3	8.6	12.8	17.1	24.5	40.9	63	63

^{*} Rotation direction shows the same _____ color as the motor. In other cases, it's the opposite.

^{*} Flat Gearbox viewed from front side is opposite rotation direction with motor.

^{*} Flat Gearbox viewed from back side is same rotation direction with motor.



Allowed overhang load and allowed thrust

Product name				Allowed ov		Allowed thrust load		
		Deceleration ratio		of output part		of output part	Allowed ti	rust load
			N	kgf	N	kgf	N	kgf
		5	100	10	150	15		
	K6LH30N2 + K6H□B	10,15,20	150	15	200	20	40	4
		30,50,100,200	200	20	300	30		
		5	200	20	250	25		
	K8LH50N2 + K8H□B	10,15,20	300	30	350	35	100	10
		30,50,100,200	450	45	550	55		
		5	300	30	400	40		15
	K9LH100N2 + K9H□B	10,15,20	400	40	500	50	150	
		30,50,100,200	500	50	650	65		
GEARED MOTOR	K10LH200N2 (K10LH400N9) + K10H□BU	5,10,15,20	550	55	800	80	200	20
		30,50	1000	100	1250	125	300	30
		100,200	1400	140	1700	170	400	40
	K6LH30N2 + K6H□BTH	5,10	450	45	370	37	200	20
		15~200	500	50	400	40	200	
	K8LH50N2	5,10	800	80	660	66	400	40
	+ K8H□BTH	15~200	1200	120	1000	100	400	40
		5,10	900	90	770	77		
	K9LH100N2 + K9H□BTH	15,20	1300	130	1110	111	500	50
		30,50,100,200	1500	150	1280	128		
	K6LS	30N2	70	7	100	10		
MOTOR	K8LS	50N2	120	12	140	14	·Be careful not to weigh thr If it's inevitable, keep it und	
IVIOTOR	K9LS1	100N2	160	16	170	17	50% of the r	notor weight.
	K10LS200N2	,K10LS400N9	197	19.7	220	22		

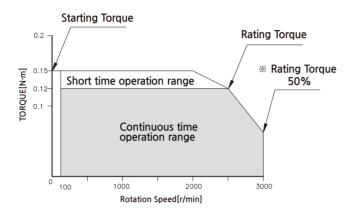
 $[\]star$ In \square of name, it represents a deceleration ratio.

 $[\]star$ Permissible overhang load can be with drawn by calulation.

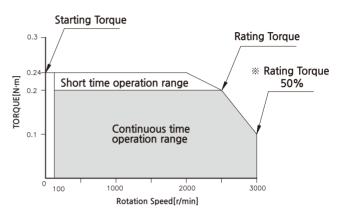


Rotation speed- torque characteristic

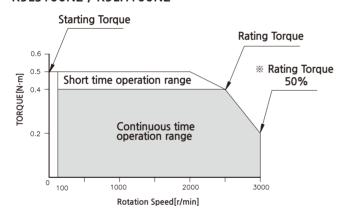
K6LS30N2 / K6LH30N2



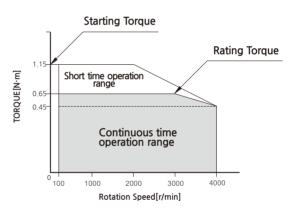
K8LS50N2 / K8LH50N2



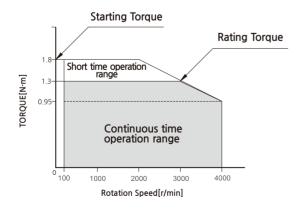
K9LS100N2 / K9LH100N2



K10LS200N2/K10LH200N2



K10LS400N9/K10LH400N9



* DC24V is the value without cable extension.



□90mm

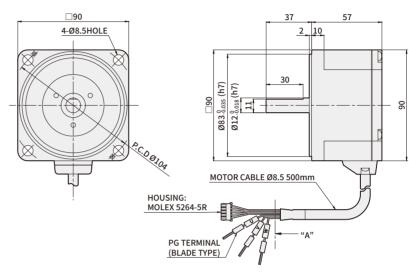
DC24V Input

DIMENSIONS

K9LS100N2

(Weight: 1.3Kg)

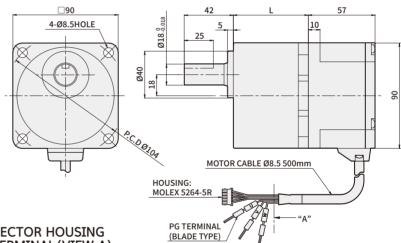




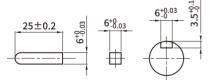
K9LH100N2 + K9H□B

(weight: 2.6Kg)

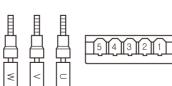




*KEY · KEY GROOVE (ACCESSORY)



* CONNECTOR HOUSING & PGTERMINAL (VIEW A)



DECELERATION

PIN No.	COLOR	SIGNAL
1	BROWN	Hu
2	WHITE	Hv
3	ORANGE	Hw
4	GREEN	Ground
5	YELLOW	Vcc
-	BLUE	U
-	PURPLE	V
-	GRAY	W

MOTOR PRODUCT NAME	GEARHEAD PRODUCT NAME	DECELERATION RATIO	L	FIXING BOLT
		5~20	45	M8 P1.25×75
K9LH100N2	К9Н□В	30~100	58	M8 P1.25×90
		200	64	M8 P1 25×95

^{*} In □ of name, it represents a deceleration ratio.

^{*} Geared motor is included with fixing blolt set. (flat washer, spring washer, hexagonal nut 4pcs each)

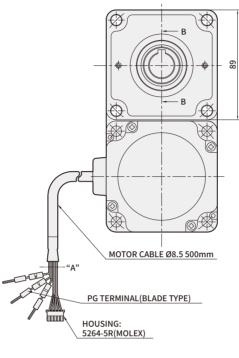


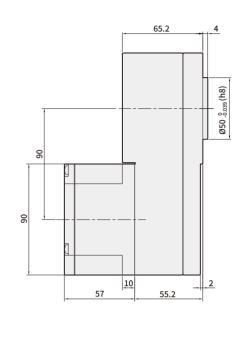
DIMENSIONS

K9LH100N2 + K9H□BTH

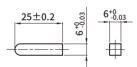
(Weight: 3.4Kg)





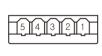


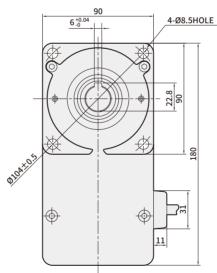
* KEY (ACCESSORY)

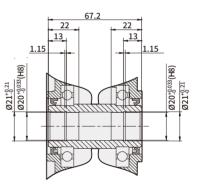


* CONNECTOR HOUSING & PGTERMINAL (VIEW A)









SECTION B-B

PIN No.	COLOR	SIGNAL
1	BROWN	Hu
2	WHITE	Hv
3	ORANGE	Hw
4	GREEN	Ground
5	YELLOW	Vcc
-	BLUE	U
-	PURPLE	V
-	GRAY	W
	-	-

MOTOR PRODUCT NAME	GEARHEAD PRODUCT NAME	DECELERATION RATIO	FIXING BOLT
K9LH100N2	К9Н□ВТН	5~200	M8 P1.25×90

- * In □ of name, it represents a deceleration ratio.
- * Mounting bolt sets are included in flat type gearbox. M8×90L (flat washer, spring washer, hexagonal nut 4pcs each)



Specification

Product		GEAR TYPE	K6LH30N2	K8LH50N2	K9LH100N2	K10LH200N2	K10LH400N9	
name		STRAIGHT TYPE	K6LS30N2	K8LS50N2	K9LS100N2	K10LS200N2	K10LS400N9	
Rating output (continuous) W			30	50	100	200	400	
	Rating vol	tage V		DC	24		DC 48	
Power	Rating vol	tage allowance			±10%			
input	Rating inp	ut current A	2.1	3.1	6	13	11	
	Rating out	tput current A	3.7	5.4	9.8	25	18	
Rating to	orque	N·m(kgf·cm)	0.12	0.2	0.4	0.65	1.3	
Starting	torque	N·m(kgf·cm)	0.15	0.24 0.5 1.15		1.15	1.8	
Rating ro	tation speed	r/min		2500	3000			
Speed co	ntrol range	r/min	100~3000 10)~4000	
moment o	inertia load f round shaft ype	J×10⁻⁴ kg·m²	1.8	3.3	5.6	8.75	15	
Rotor ine	rtia moment	J×10⁻⁴ kg·m²	0.086	0.234	0.61	0.61	0.66	
		Load	Less than or equal to ±1%: condition 0-rated torque, rated rotation speed, rated voltage, room temperature					
Speed change rate		Voltage	Less than or equal to ±1%: condition rating voltage ±10%, rating rotation speed, no load, room temperature					
idic		Temperature	Less than or equal to ±1%: condition surrounding temperature 0~+40°C, rating rotation speed, no load, rating voltage					

- * The usage duration for starting torque is within 5 seconds at less than 2000 r/min
- * Each specification value is the characteristic of motor by itself

Common specifications

Product name	Specification
Rotation speed setting method	 Set up by external potentiometer Set up by external DC 0~5V
Acceleration time deceleration time	0.5~10 seconds: set at 2000 r/min when there is no load (it may change depending on the size of the load) Accleration time and deceleration control equipment to control at the same time
Input signal	Internal full-up input method, external input voltage read as greater than 2v high(off) same at all input ports
Output signal	Open collector output, common for speed out/alarm out, if input voltage from out side is applied to connector #2 pin, then it comes out through the applied power. Everything else is internal 5V ouput UI(CTRL)
Protection function	If the following protection mode comes on, cotrol unit alarm signal is shown. Motor stops automatically. Overload protection mode: If torque that is greater than the rating is applied to the motor for more than 5 seconds Overvoltage protection: If voltage applied to the control unit goes over the upper bound of the rating allowance Open phase protection: If cable sensor line gets disconnected during motor operation Undervoltage protection: If voltage applied to the control unit is less than the lower bound of th rating voltage allowance Over speed protection: If motor rotation speed is faster than 2500 r/min
Motor insulation class	E TYPE(120°c)
Maximum extension distance	MOTOR - CONTROL UNIT 2m
Rated time	Continuous

^{*} Like weight carried being downwards, L SERIES cannot control motor speed through weight.

Motor gets stopped automatically through overvoltage protection of load is being carried downwards or it is heavier than allowed load inertia.





Normal specifications

Iter	ns	Motor	Control unit				
Insulation I	Resistance	After being operated continuously at room temperature and humidity, the value measured between coil and vase by DC 500V MEGA is greater than or equal to 100№	After being operated continuously at room temperature and humidity, the value measured between heatproof plate and power input is greater than or equal to 100MQ				
Dielectric	Strength	After being operated continuously at room temperature and humidity, there shouldn't be any problem between coil and case even when AC 0.5kV is applied for 1 minute	No problem when 50Hz, AC 0.5kV is applied for one minute No problem when AC 0.5kV is applied for one minute				
	Used Ambient temperature	0℃~+50℃ (shc	ould not freeze)				
	Used Ambient Humidity	less than or equal to 8	85% (not from dews)				
Used	Vibration	Altitude less than 1000m					
environment	Ambient environment	Cannot be used under special circumstances such as with corrosive gas, dust, radioactive material, magnetic and vacuum					
	Vibration	the JIS C 60068-2-6 sine v Frequency range : 10~55Hz	tion or huge impact according to vave vibration test method r, peak amplitude: 0.15mm, ,Z), number of sweeps: 20 times				
	Ambient temperature	-25 ~ +70° (sh	ould not freeze)				
Conservation environment	Ambient Humidity	less than or equal to 8	35% (not form dews)				
	Altitude	Altitude less	than 3000m				
Insulatio	on class	UL, CSA STANDARD A TYPE(105°c), EN STANDARD E TYPE(120°c)					
Protection	on class	IP65	IP00				

- * Preservation environment is a short-term value, which includes transportation.
- * Do not measure insulation resistance and pressure resistance while motor and driver are connected

Delivery effciency of gearhead

	Deceleration ratio	5	10	15	20	30	50	100	200	
	К6Н□В		90)%		86%			81%	
	K8H□B		90)%		86%			81%	
Product	К9Н□В		90%				86%			
name	K10H□BU		90)%		86% 81%			%	
	K6H□BTH	80%				85%				
	K8H□BTH		85				35%			
	K9H□BTH				85	%				



→ Allowed torque of combination type

Product	Decelerat	ion ratio	5	10	15	20	30	50	100	200
name Speed control ra		range[r/min]	20~600	10~300	6.7~200	5~150	3.3~100	2~60	1~30	0.5~15
KEDII	30N2 + K6H□B	100~2500r/min	0.54	1.1	1.6	2.2	3.1	5.2	6	6
КОВП	SUNZ + KOHLIB	3000r/min	0.3	0.54	0.81	1.1	1.5	2.6	5.2	6
ГО ВП	50N2 + K8H□B	100~2500r/min	0.9	1.8	2.7	3.6	5.2	8.6	16	16
КОВП	DUNZ + KOHLIB	3000r/min	0.45	0.9	1.4	1.8	2.6	4.3	8.6	16
KOBILI	100N2 + K9H□B	100~2500r/min	1.8	3.6	5.4	7.2	10.3	17.2	30	30
KSDU	IUUNZ + K9HLB	3000r/min	0.9	1.8	2.7	3.6	5.2	8.6	17.2	30
V C D L I 2	100~2500r/min		0.48	1	1.5	2	3.1	5.1	10.2	17
Ковнз	ON2 + K6H□BTH	3000r/min	0.2	0.51	0.77	1	1.5	2.6	5.1	10.2
KODITE	OND I KOHEDTH	100~2500r/min	0.85	1.7	2.6	3.4	5.1	8.5	17	34
Ковно	0N2 + K8H□BTH	3000r/min	4.3	8.5	13	17	26	4.3	8.5	17
KODIII	ONI - KOUDDIU	100~2500r/min	1.7	3.4	5.1	6.8	10.2	17	34	68
КЭВНІС	OON2 + K9H□BTH	3000r/min	0.85	1.7	2.6	3.4	5.1	8.5	17	34
Product	Decelerat	ion ratio	5	10	15	20	30	50	100	200
name	Speed control	range[r/min]	20~800	10~400	6.7~267	5~200	3.3~133	2~80	1~40	0.5~20
V101112	00N3 + K10H□BII	100~3000r/min	2.9	5.9	8.8	11.7	16.8	28	52.7	70
K TULHZ	K10LH200N2 + K10H□BU 4000r/min		2.0	4.1	6.1	8.1	11.6	19.4	36.5	63
K101114	00N0 + K10H=PH	100~3000r/min	5.9	11.7	17.6	23.4	33.5	55.9	70	70
K TULH4	00N9 + K10H□BU	4000r/min	4.3	8.6	12.8	17.1	24.5	40.9	63	63

^{*} Rotation direction shows the same _____ color as the motor. In other cases, it's the opposite.

^{*} Flat Gearbox viewed from front side is opposite rotation direction with motor.

^{*} Flat Gearbox viewed from back side is same rotation direction with motor.



Allowed overhang load and allowed thrust

				Allowed ov	erhand load		Allowed thrust load	
Produ	ct name	Deceleration ratio		of output part		of output part	Allowed ti	rust load
			N	kgf	N	kgf	N	kgf
		5	100	10	150	15		
	K6LH30N2 + K6H□B	10,15,20	150	15	200	20	40	4
		30,50,100,200	200	20	300	30		
		5	200	20	250	25		
	K8LH50N2 + K8H□B	10,15,20	300	30	350	35	100	10
		30,50,100,200	450	45	550	55		
		5	300	30	400	40		
	K9LH100N2 + K9H□B	10,15,20	400	40	500	50	150	15
		30,50,100,200	500	50	650	65		
GEARED MOTOR	K10LH200N2 (K10LH400N9) + K10H□BU	5,10,15,20	550	55	800	80	200	20
		30,50	1000	100	1250	125	300	30
		100,200	1400	140	1700	170	400	40
	K6LH30N2	5,10	450	45	370	37	200	20
	+ K6H□BTH	15~200	500	50	400	40	200	
	K8LH50N2	5,10	800	80	660	66	400	40
	+ K8H□BTH	15~200	1200	120	1000	100	400	40
		5,10	900	90	770	77		
	K9LH100N2 + K9H□BTH	15,20	1300	130	1110	111	500	50
		30,50,100,200	1500	150	1280	128		
	K6LS	30N2	70	7	100	10		
MOTOR	K8LS	50N2	120	12	140	14	·Be careful not to weigh thru If it's inevitable, keep it und 50% of the motor weight	
IVIOTOR	K9LS1	100N2	160	16	170	17		
	K10LS200N2	,K10LS400N9	197	19.7	220	22		

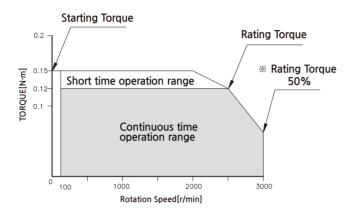
 $[\]star$ In \square of name, it represents a deceleration ratio.

 $[\]star$ Permissible overhang load can be with drawn by calulation.

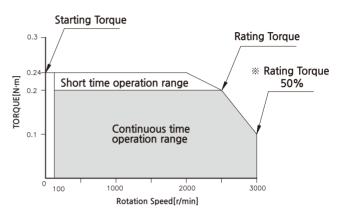


Rotation speed- torque characteristic

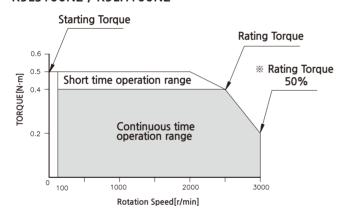
K6LS30N2 / K6LH30N2



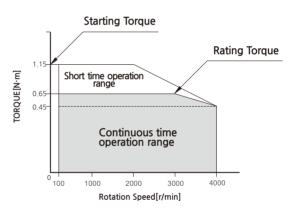
K8LS50N2 / K8LH50N2



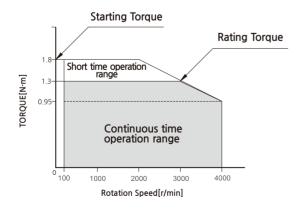
K9LS100N2 / K9LH100N2



K10LS200N2/K10LH200N2



K10LS400N9/K10LH400N9



* DC24V is the value without cable extension.

GGM GGM GEARED MOTOR

USHLESS DC MOTOR UNIT - L Series



□104mm

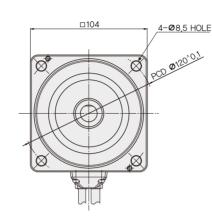
DC24V Input DC48V Input

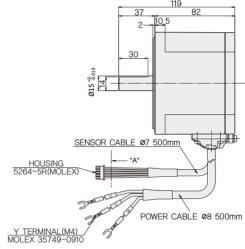
DIMENSIONS

K10LS200N2 (24V) K10LS400N9 (48V)

(Weight: 2.4Kg)



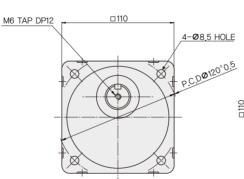


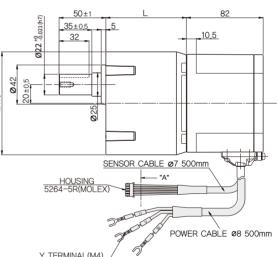


K10LH200N2 + K10H□BU K10LH400N9 + K10H□BU

(Weight: 5.4Kg)

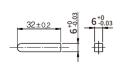




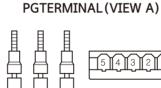


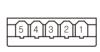
* KEY · KEY GROOVE (ACCESSORY)

© KEY O KEY GROOVE









*CONNECTOR HOUSING &

MOTOR PRODUCT NAME			L	FIXING BOLT	
K10LH200N2		5~20	60	M8 P1.25×95	
	K10H□BU	30~50	72	M8 P1.25×110	
K10LH400N9		100~200	86	M8 P1.25×120	

PIN No.	COLOR	SIGNAL
1	BROWN	Hu
2	WHITE	Hv
3	ORANGE	Hw
4	GREEN	Ground
5	YELLOW	Vcc
-	BLUE	U
-	PURPLE	V
-	GRAY	W

- * In \square of name, it represents a deceleration ratio.
- * Geared motor is included with fixing bolt set (normal WASHER, SPRING, WASHER, cube nut; 4 each)





Specification

Product		GEAR TYPE	K6LH30N2	K8LH50N2	K9LH100N2	K10LH200N2	K10LH400N9	
name		STRAIGHT TYPE	K6LS30N2	K8LS50N2	K9LS100N2	K10LS200N2	K10LS400N9	
Rating output (continuous) W			30	50	100	200	400	
	Rating vol	tage V		DC	24		DC 48	
Power	Rating vol	tage allowance			±10%			
input	Rating inp	ut current A	2.1	3.1	6	13	11	
	Rating out	tput current A	3.7	5.4	9.8	25	18	
Rating to	orque	N·m(kgf·cm)	0.12	0.2	0.4	0.65	1.3	
Starting	torque	N·m(kgf·cm)	0.15	0.24 0.5 1.15		1.15	1.8	
Rating ro	tation speed	r/min		2500	3000			
Speed co	ntrol range	r/min	100~3000 10)~4000	
moment o	inertia load f round shaft ype	J×10⁻⁴ kg·m²	1.8	3.3	5.6	8.75	15	
Rotor ine	rtia moment	J×10⁻⁴ kg·m²	0.086	0.234	0.61	0.61	0.66	
		Load	Less than or equal to ±1%: condition 0-rated torque, rated rotation speed, rated voltage, room temperature					
Speed change rate		Voltage	Less than or equal to ±1%: condition rating voltage ±10%, rating rotation speed, no load, room temperature					
idic		Temperature	Less than or equal to ±1%: condition surrounding temperature 0~+40°C, rating rotation speed, no load, rating voltage					

- * The usage duration for starting torque is within 5 seconds at less than 2000 r/min
- * Each specification value is the characteristic of motor by itself

Common specifications

Product name	Specification
Rotation speed setting method	 Set up by external potentiometer Set up by external DC 0~5V
Acceleration time deceleration time	0.5~10 seconds: set at 2000 r/min when there is no load (it may change depending on the size of the load) Accleration time and deceleration control equipment to control at the same time
Input signal	Internal full-up input method, external input voltage read as greater than 2v high(off) same at all input ports
Output signal	Open collector output, common for speed out/alarm out, if input voltage from out side is applied to connector #2 pin, then it comes out through the applied power. Everything else is internal 5V ouput UI(CTRL)
Protection function	If the following protection mode comes on, cotrol unit alarm signal is shown. Motor stops automatically. Overload protection mode: If torque that is greater than the rating is applied to the motor for more than 5 seconds Overvoltage protection: If voltage applied to the control unit goes over the upper bound of the rating allowance Open phase protection: If cable sensor line gets disconnected during motor operation Undervoltage protection: If voltage applied to the control unit is less than the lower bound of th rating voltage allowance Over speed protection: If motor rotation speed is faster than 2500 r/min
Motor insulation class	E TYPE(120°c)
Maximum extension distance	MOTOR - CONTROL UNIT 2m
Rated time	Continuous

^{*} Like weight carried being downwards, L SERIES cannot control motor speed through weight.

Motor gets stopped automatically through overvoltage protection of load is being carried downwards or it is heavier than allowed load inertia.





Normal specifications

Iter	ns	Motor	Control unit				
Insulation I	Resistance	After being operated continuously at room temperature and humidity, the value measured between coil and vase by DC 500V MEGA is greater than or equal to 100№	After being operated continuously at room temperature and humidity, the value measured between heatproof plate and power input is greater than or equal to 100MQ				
Dielectric	Strength	After being operated continuously at room temperature and humidity, there shouldn't be any problem between coil and case even when AC 0.5kV is applied for 1 minute	No problem when 50Hz, AC 0.5kV is applied for one minute No problem when AC 0.5kV is applied for one minute				
	Used Ambient temperature	0℃~+50℃ (shc	ould not freeze)				
	Used Ambient Humidity	less than or equal to 8	85% (not from dews)				
Used	Vibration	Altitude less than 1000m					
environment	Ambient environment	Cannot be used under special circumstances such as with corrosive gas, dust, radioactive material, magnetic and vacuum					
	Vibration	the JIS C 60068-2-6 sine v Frequency range : 10~55Hz	tion or huge impact according to vave vibration test method r, peak amplitude: 0.15mm, ,Z), number of sweeps: 20 times				
	Ambient temperature	-25 ~ +70° (sh	ould not freeze)				
Conservation environment	Ambient Humidity	less than or equal to 8	35% (not form dews)				
	Altitude	Altitude less	than 3000m				
Insulatio	on class	UL, CSA STANDARD A TYPE(105°c), EN STANDARD E TYPE(120°c)					
Protection	on class	IP65	IP00				

- * Preservation environment is a short-term value, which includes transportation.
- * Do not measure insulation resistance and pressure resistance while motor and driver are connected

Delivery effciency of gearhead

	Deceleration ratio	5	10	15	20	30	50	100	200	
	К6Н□В		90)%		86%			81%	
	K8H□B		90)%		86%			81%	
Product	К9Н□В		90%				86%			
name	K10H□BU		90)%		86% 81%			%	
	K6H□BTH	80%				85%				
	K8H□BTH		85				35%			
	K9H□BTH				85	%				



→ Allowed torque of combination type

Product	Deceleration ratio		5	10	15	20	30	50	100	200
name	Speed control range[r/min]		20~600	10~300	6.7~200	5~150	3.3~100	2~60	1~30	0.5~15
K6BH30N2 + K6H□B		100~2500r/min	0.54	1.1	1.6	2.2	3.1	5.2	6	6
		3000r/min	0.3	0.54	0.81	1.1	1.5	2.6	5.2	6
K8BH50N2 + K8H□B 100~2500r/min 3000r/min		0.9	1.8	2.7	3.6	5.2	8.6	16	16	
		3000r/min	0.45	0.9	1.4	1.8	2.6	4.3	8.6	16
K9BH100N2 + K9H□B 100~2500r/min 3000r/min		1.8	3.6	5.4	7.2	10.3	17.2	30	30	
		3000r/min	0.9	1.8	2.7	3.6	5.2	8.6	17.2	30
K6BH30N2 + K6H□BTH 100~2500r/min 3000r/min		0.48	1	1.5	2	3.1	5.1	10.2	17	
		3000r/min	0.2	0.51	0.77	1	1.5	2.6	5.1	10.2
K8BH50N2 + K8H□BTH 100~2500r/min 3000r/min		0.85	1.7	2.6	3.4	5.1	8.5	17	34	
		3000r/min	4.3	8.5	13	17	26	4.3	8.5	17
K9BH100N2 + K9H□BTH 100~2500r/min 3000r/min		1.7	3.4	5.1	6.8	10.2	17	34	68	
		3000r/min	0.85	1.7	2.6	3.4	5.1	8.5	17	34
Product name	Deceleration ratio		5	10	15	20	30	50	100	200
	Speed control range[r/min]		20~800	10~400	6.7~267	5~200	3.3~133	2~80	1~40	0.5~20
V101112	00N2 + K40H=PH	100~3000r/min	2.9	5.9	8.8	11.7	16.8	28	52.7	70
K10LH200N2 + K10H□BU		4000r/min	2.0	4.1	6.1	8.1	11.6	19.4	36.5	63
K10LH400N9 + K10H□BU 100~3000r/min 4000r/min		5.9	11.7	17.6	23.4	33.5	55.9	70	70	
		4000r/min	4.3	8.6	12.8	17.1	24.5	40.9	63	63

^{*} Rotation direction shows the same _____ color as the motor. In other cases, it's the opposite.

^{*} Flat Gearbox viewed from front side is opposite rotation direction with motor.

^{*} Flat Gearbox viewed from back side is same rotation direction with motor.



Allowed overhang load and allowed thrust

Product name		Deceleration ratio		Allowed ov				
			From the end of output part 10mm			of output part	Allowed thrust load	
			N	kgf	N	kgf	N	kgf
	K6LH30N2 + K6H□B	5	100	10	150	15	40	4
		10,15,20	150	15	200	20		
		30,50,100,200	200	20	300	30		
	K8LH50N2 + K8H□B	5	200	20	250	25	100	10
		10,15,20	300	30	350	35		
		30,50,100,200	450	45	550	55		
	K9LH100N2 + K9H□B	5	300	30	400	40	150	15
		10,15,20	400	40	500	50		
		30,50,100,200	500	50	650	65		
GEARED MOTOR		5,10,15,20	550	55	800	80	200	20
		30,50	1000	100	1250	125	300	30
		100,200	1400	140	1700	170	400	40
	K6LH30N2 + K6H□BTH	5,10	450	45	370	37	200	20
		15~200	500	50	400	40	200	
	K8LH50N2 + K8H□BTH	5,10	800	80	660	66	400	40
		15~200	1200	120	1000	100	400	
	K9LH100N2 + K9H□BTH	5,10	900	90	770	77		50
		15,20	1300	130	1110	111	500	
		30,50,100,200	1500	150	1280	128		
	K6LS30N2		70	7	100	10		
MOTOR	K8LS50N2		120	12	140	14		to weigh thrust. e, keep it under
IVIOTOR	K9LS100N2		160	16	170	17	50% of the r	notor weight.
	K10LS200N2,K10LS400N9		197	19.7	220	22		

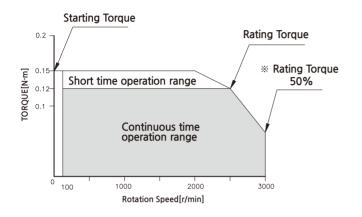
 $[\]star$ In \square of name, it represents a deceleration ratio.

 $[\]star$ Permissible overhang load can be with drawn by calulation.

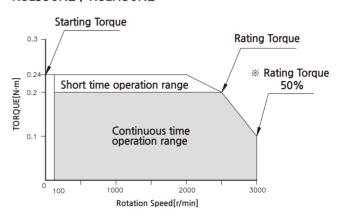


Rotation speed- torque characteristic

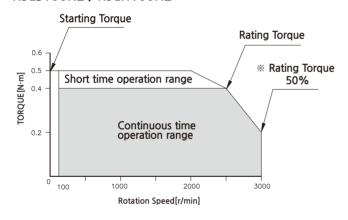
K6LS30N2 / K6LH30N2



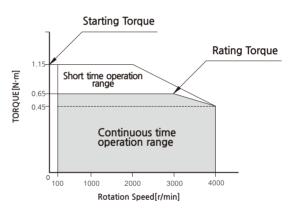
K8LS50N2 / K8LH50N2



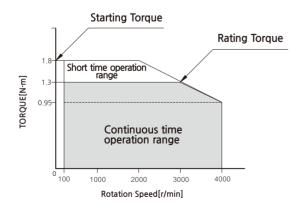
K9LS100N2 / K9LH100N2



K10LS200N2/K10LH200N2



K10LS400N9/K10LH400N9



* DC24V is the value without cable extension.